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## LAMPIRAN

### Lampiran 1 List Program Arduino

#### 1. List Program Pada Arduino Mega 2560

```
/*
   SKRIPSI
ALAT PEMBUAT KOPI OTOMATIS BERBASIS ARDUINO
   MEGA 2560 DENGAN RFID CARD
   SEBAGAI ALAT PEMBAYARAN

   NAMA : MUHAMMAD ASHIF
   NO. REG : 5215117015
   PEND. TEKNIK ELEKTRONIKA
   UNIVERSITAS NEGERI JAKARTA
*/
#include <SoftwareSerial.h>
#include <OneWire.h>

OneWire Sensor1(6);
OneWire Sensor2(7);
OneWire Sensor3(8);

int NilaiSensor1;
int NilaiSensor2;
int NilaiSensor3;
int tx      = 1;
int rx      = 0;
int echoPin = 12;
int trigPin = 13;

int pd1      = A0;
int pd2      = A1;
int pd3      = A2;

int kran1    = 9;
int kran2    = 10;
int kran3    = 11;

int led1     = 22;
int led2     = 24;
int led3     = 26;
int panas1   = 28;
int panas2   = 30;
int panas3   = 32;

int pdA, pdB, pdC, ultra, distance;

SoftwareSerial bluetooth(tx, rx);

String readString;

void setup() {
  Serial.begin(9600);
  pinMode(tx, OUTPUT);
```

```

pinMode(rx,      INPUT);
pinMode(trigPin, OUTPUT);
pinMode(echoPin, INPUT);
pinMode(pd1,     INPUT);
pinMode(pd2,     INPUT);
pinMode(pd3,     INPUT);
pinMode(led1,    OUTPUT);
pinMode(led2,    OUTPUT);
pinMode(led3,    OUTPUT);
pinMode(kran1,   OUTPUT);
pinMode(kran2,   OUTPUT);
pinMode(kran3,   OUTPUT);
pinMode(panas1,  OUTPUT);
pinMode(panas2,  OUTPUT);
pinMode(panas3,  OUTPUT);
}
void baca_input()
{
    pdA    = analogRead(pd1);
    pdB    = analogRead(pd2);
    pdC    = analogRead(pd3);
    ultra  = digitalRead(echoPin);

    long duration, distance;
    digitalWrite(trigPin, LOW); // Added this line
    delayMicroseconds(2); // Added this line
    digitalWrite(trigPin, HIGH);
//    delayMicroseconds(1000); - Removed this line
    delayMicroseconds(10); // Added this line
    digitalWrite(trigPin, LOW);
    duration = pulseIn(echoPin, HIGH);
    distance = (duration/2) / 29.1;
    delay(500);
}

void baca_bluetooth()
{
    while (Serial.available())
    {
        delay (3);
        char c = Serial.read();
        readString += c;
    }
    if (readString.length() >0)
    {
        Serial.println(readString);
        if (readString == "k1")
        {
            kopil();
        }

        if (readString == "k2")
        {
            kopi2();
        }

        if (readString == "k3")
        {
            kopi3();
        }
    }
}

```

```

    }

    if (readString == "s1")
    {
        kopi4();
    }

    if (readString == "s2")
    {
        kopi5();
    }

    if (readString == "s3")
    {
        kopi6();
    }

    if (readString == "b1")
    {
        kopi7();
    }

    if (readString == "b2")
    {
        kopi8();
    }

    if (readString == "b3")
    {
        kopi9();
    }
}

void kopi1()
{
    digitalWrite(led1,      HIGH);
    if (pdA>300 && pdB<300 && pdC<300)
    {
        digitalWrite(kran1,  HIGH);
        if (distance<=15)
            digitalWrite(kran1,  LOW);
        digitalWrite(led1,      LOW);
    }
    else
    {
        digitalWrite(kran1,  LOW);
    }
}

void kopi2()
{
    digitalWrite(led1,      HIGH);
    if (pdA>300 && pdB<300 && pdC<300)
    {
        digitalWrite(kran2,  HIGH);
        if (distance<=15)
            digitalWrite(kran2,  LOW);
        digitalWrite(led1,      LOW);
    }
}

```

```

        }
    else
    {
        digitalWrite(kran2,  LOW);
    }
}

void kopi3()
{
    digitalWrite(led1,      HIGH);
    if (pdA>300 && pdB<300 && pdC<300)
    {
        digitalWrite(kran3,  HIGH);
        if (distance<=15)
            digitalWrite(kran3,  LOW);
        digitalWrite(led1,      LOW);
    }
    else
    {
        digitalWrite(kran3,  LOW);
    }
}

void kopi4()
{
    digitalWrite(led2,      HIGH);
    if (pdA>300 && pdB>300 && pdC<300)
    {
        digitalWrite(kran1,  HIGH);
        if (distance<=12)
            digitalWrite(kran1,  LOW);
        digitalWrite(led2,      LOW);
    }
    else
    {
        digitalWrite(kran2,  LOW);
    }
}

void kopi5()
{
    digitalWrite(led2,      HIGH);
    if (pdA>300 && pdB>300 && pdC<300)
    {
        digitalWrite(kran2,  HIGH);
        if (distance<=12)
            digitalWrite(kran2,  LOW);
        digitalWrite(led2,      LOW);
    }
    else
    {
        digitalWrite(kran2,  LOW);
    }
}

void kopi6()
{
    digitalWrite(led2,      HIGH);
    if (pdA>300 && pdB>300 && pdC<300)

```

```

    {
        digitalWrite(kran3,  HIGH);
        if (distance<=12)
            digitalWrite(kran3,  LOW);
            digitalWrite(led2,  LOW);
    }
    else
    {
        digitalWrite(kran3,  LOW);
    }
}

void kopi7()
{
    digitalWrite(led3,      HIGH);
    if (pdA>300 && pdB>300 && pdC>300)
    {
        digitalWrite(kran1,  HIGH);
        if (distance<=9)
            digitalWrite(kran1,  LOW);
            digitalWrite(led3,  LOW);
    }
    else
    {
        digitalWrite(kran1,  LOW);
    }
}

void kopi8()
{
    digitalWrite(led3,      HIGH);
    if (pdA>300 && pdB>300 && pdC>300)
    {
        digitalWrite(kran2,  HIGH);
        if (distance<=9)
            digitalWrite(kran2,  LOW);
            digitalWrite(led3,  LOW);
    }
    else
    {
        digitalWrite(kran2,  LOW);
    }
}

void kopi9()
{
    digitalWrite(led3,      HIGH);
    if (pdA>300 && pdB>300 && pdC>300)
    {
        digitalWrite(kran3,  HIGH);
        if (distance<=9)
            digitalWrite(kran3,  LOW);
            digitalWrite(led3,  LOW);
    }
    else
    {
        digitalWrite(kran3,  LOW);
    }
}

```

```

void suhu()
{
    DS18B20_1();
    Serial.print("Sensor1 = ");
    Serial.println(NilaiSensor1);
    DS18B20_2();
    Serial.print("Sensor2 = ");
    Serial.println(NilaiSensor2);
    DS18B20_3();
    Serial.print("Sensor3 = ");
    Serial.println(NilaiSensor3);

    if (NilaiSensor1<=78)
    {
        digitalWrite(panas1, HIGH);
    }
    else
    {
        digitalWrite(panas1, LOW);
    }

    if (NilaiSensor2<=80)
    {
        digitalWrite(panas2, HIGH);
    }
    else
    {
        digitalWrite(panas2, LOW);
    }

    if (NilaiSensor1<=90)
    {
        digitalWrite(panas3, HIGH);
    }
    else
    {
        digitalWrite(panas3, LOW);
    }
}

void DS18B20_1()
{
    byte i;
    byte present = 0;
    byte type_s;
    byte data[12];
    byte addr[8];
    float celsius, fahrenheit;

    if ( !Sensor1.search(addr)) {
        Sensor1.reset_search();
        delay(250);
        return;
    }

    for( i = 0; i < 8; i++) {
}

```

```

if (OneWire::crc8(addr, 7) != addr[7]) {
    return;
}
switch (addr[0]) {
case 0x10:
    type_s = 1;
    break;
case 0x28:
    type_s = 0;
    break;
case 0x22:
    type_s = 0;
    break;
default:
    return;
}

Sensor1.reset();
Sensor1.select(addr);
Sensor1.write(0x44, 1);           // start conversion, with
parasite power on at the end

delay(1000);        // maybe 750ms is enough, maybe not

present = Sensor1.reset();
Sensor1.select(addr);
Sensor1.write(0xBE);           // Read Scratchpad
for ( i = 0; i < 9; i++) {           // we need 9 bytes
    data[i] = Sensor1.read();
}
int16_t raw = (data[1] << 8) | data[0];
if (type_s) {
    raw = raw << 3; // 9 bit resolution default
    if (data[7] == 0x10) {
        raw = (raw & 0xFFFF) + 12 - data[6];
    }
}
else {
    byte cfg = (data[4] & 0x60);
    if (cfg == 0x00) raw = raw & ~7; // 9 bit resolution, 93.75
ms
    else if (cfg == 0x20) raw = raw & ~3; // 10 bit res, 187.5 ms
    else if (cfg == 0x40) raw = raw & ~1; // 11 bit res, 375 ms
}
celsius = (float)raw / 16.0;
fahrenheit = celsius * 1.8 + 32.0;
NilaiSensor1 = celsius;
}

void DS18B20_2()
{
byte i;
byte present = 0;
byte type_s;
byte data[12];
byte addr[8];
float celsius, fahrenheit;

```

```

if ( !Sensor2.search(addr) ) {
    Sensor2.reset_search();
    delay(250);
    return;
}

for( i = 0; i < 8; i++) {

if (OneWire::crc8(addr, 7) != addr[7]) {
    return;
}
switch (addr[0]) {
case 0x10:
    type_s = 1;
    break;
case 0x28:
    type_s = 0;
    break;
case 0x22:
    type_s = 0;
    break;
default:
    return;
}

Sensor2.reset();
Sensor2.select(addr);
Sensor2.write(0x44, 1);           // start conversion, with
parasite power on at the end

delay(1000);        // maybe 750ms is enough, maybe not

present = Sensor2.reset();
Sensor2.select(addr);
Sensor2.write(0xBE);           // Read Scratchpad
for ( i = 0; i < 9; i++) {           // we need 9 bytes
    data[i] = Sensor2.read();
}
int16_t raw = (data[1] << 8) | data[0];
if (type_s) {
    raw = raw << 3; // 9 bit resolution default
    if (data[7] == 0x10) {
        raw = (raw & 0xFF0) + 12 - data[6];
    }
}
else {
    byte cfg = (data[4] & 0x60);
    if (cfg == 0x00) raw = raw & ~7; // 9 bit resolution, 93.75
ms
    else if (cfg == 0x20) raw = raw & ~3; // 10 bit res, 187.5 ms
    else if (cfg == 0x40) raw = raw & ~1; // 11 bit res, 375 ms
}
celsius = (float)raw / 16.0;
fahrenheit = celsius * 1.8 + 32.0;
NilaiSensor2 = celsius;
}

void DS18B20_3()

```

```

{
    byte i;
    byte present = 0;
    byte type_s;
    byte data[12];
    byte addr[8];
    float celsius, fahrenheit;

    if ( !Sensor3.search(addr) ) {
        Sensor3.reset_search();
        delay(250);
        return;
    }

    for( i = 0; i < 8; i++) {

        if (OneWire::crc8(addr, 7) != addr[7]) {
            return;
        }
        switch (addr[0]) {
        case 0x10:
            type_s = 1;
            break;
        case 0x28:
            type_s = 0;
            break;
        case 0x22:
            type_s = 0;
            break;
        default:
            return;
        }

        Sensor3.reset();
        Sensor3.select(addr);
        Sensor3.write(0x44, 1);           // start conversion, with
parasite power on at the end

        delay(1000);      // maybe 750ms is enough, maybe not

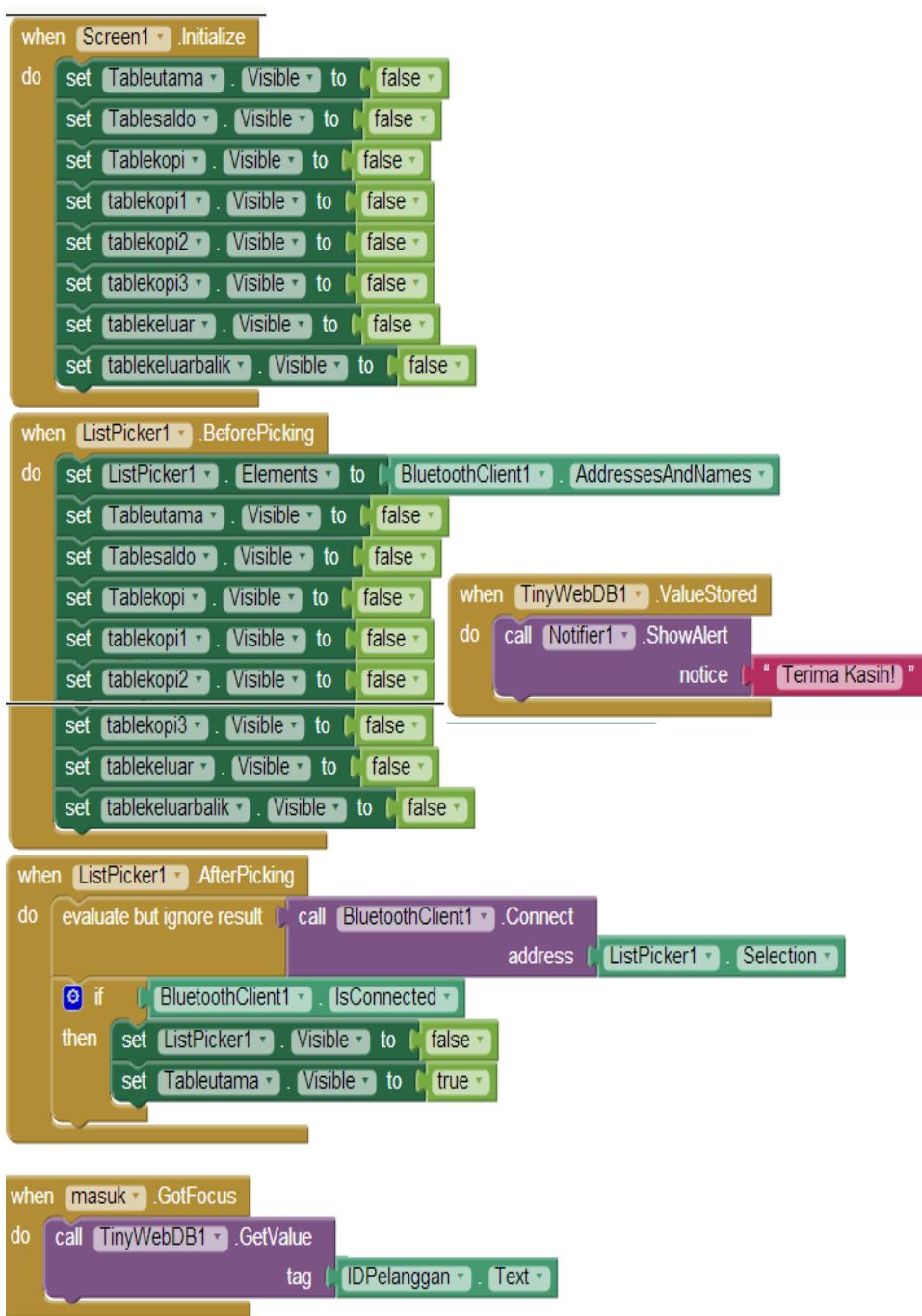
        present = Sensor3.reset();
        Sensor3.select(addr);
        Sensor3.write(0xBE);           // Read Scratchpad
        for ( i = 0; i < 9; i++) {           // we need 9 bytes
            data[i] = Sensor3.read();
        }
        int16_t raw = (data[1] << 8) | data[0];
        if (type_s) {
            raw = raw << 3; // 9 bit resolution default
            if (data[7] == 0x10) {
                raw = (raw & 0xFF0) + 12 - data[6];
            }
        }
        else {
            byte cfg = (data[4] & 0x60);
            if (cfg == 0x00) raw = raw & ~7; // 9 bit resolution, 93.75
ms
            else if (cfg == 0x20) raw = raw & ~3; // 10 bit res, 187.5 ms
        }
    }
}

```

```
    else if (cfg == 0x40) raw = raw & ~1; // 11 bit res, 375 ms
}
celsius = (float)raw / 16.0;
fahrenheit = celsius * 1.8 + 32.0;
NilaiSensor3 = celsius;
}

void loop()
{
    baca_bluetooth();
    baca_input();
    kopi1();
    kopi2();
    kopi3();
    kopi4();
    kopi5();
    kopi6();
    kopi7();
    kopi8();
    kopi9();
    suhu();
```

## Lampiran 2 Blok Program App Inventor



```

when keluar2 .Click
do set tablekopi1 .Visible to false
set tablekopi2 .Visible to false
set tablekopi3 .Visible to false
set Tablesaldo .Visible to false
set Tableutama .Visible to true
set tablekeluar .Visible to false
set tablekeluarbalik .Visible to false
set Label10 .Visible to false
set memuatsaldo .Text to " "
set IDPelanggan .Text to " "
set Hitam .Enabled to true
set luwak .Enabled to true
set capucino .Enabled to true
set deng1 .Enabled to true
set gede1 .Enabled to true
set deng2 .Enabled to true
set gede2 .Enabled to true
set deng3 .Enabled to true
set gede3 .Enabled to true

when TinyWebDB1 .WebServiceError
message
do call Notifier1 .ShowAlert
notice " Maaf, server sedang mangalami gangguan "

when TinyWebDB1 .GetValue
tagFromWebDB valueFromWebDB
do set tagFromWebDB to IDPelanggan .Text
set memuatsaldo .Text to get valueFromWebDB
set Tablesaldo .Visible to true
set Tablekopi .Visible to true
set tablekeluar .Visible to true
set Tableutama .Visible to false
set Label10 .Visible to true
if memuatsaldo .Text < 4000
then call Notifier1 .ShowAlert
notice " Maaf, Kartu Anda tidak terdaftar /Saldo Anda Tidak Cukup! "
set Hitam .Enabled to false
set luwak .Enabled to false
set capucino .Enabled to false
else if memuatsaldo .Text < 5000
then set luwak .Enabled to false
else if memuatsaldo .Text < 7000
then set capucino .Enabled to false

```

```
when Hitam .Click
do set Tablekopi .Visible to false
set tablekeluar .Visible to false
set tablekopi1 .Visible to true
set tablekeluarbalik .Visible to true
set Label10 .Visible to false
if memuatsaldo .Text < 5000
then set deng1 .Enabled to false
else if memuatsaldo .Text < 6000
then set gede1 .Enabled to false
```

```
when back .Click
do set tablekopi1 .Visible to false
set tablekopi2 .Visible to false
set tablekopi3 .Visible to false
set Tablesaldo .Visible to true
set Tablekopi .Visible to true
set tablekeluarbalik .Visible to false
set tablekeluar .Visible to true
set Label10 .Visible to false
```

```
when luwak .Click
do set Label10 .Visible to false
set Tablekopi .Visible to false
set tablekeluar .Visible to false
set tablekopi2 .Visible to true
set tablekeluarbalik .Visible to true
if memuatsaldo .Text < 6000
then set deng2 .Enabled to false
else if memuatsaldo .Text < 7000
then set gede2 .Enabled to false
```

```

when capucino .Click
do
  set Tablekopi .Visible to false
  set tablekeluar .Visible to false
  set tablekopi3 .Visible to true
  set tablekeluarbalik .Visible to true
  set Label10 .Visible to false
  if memuatsaldo .Text < 8000
    then set deng3 .Enabled to false
  else if memuatsaldo .Text < 10000
    then set gede3 .Enabled to false
  end if

when cil1 .Click
do
  set memuatsaldo .Text to memuatsaldo .Text - 4000
  call TinyWebDB1 .StoreValue
    tag IDPelanggan .Text
    valueToStore memuatsaldo .Text
  call BluetoothClient1 .SendText
    text "k1"
  set tablekopi1 .Visible to false
  set Tablesaldo .Visible to false
  set tablekeluarbalik .Visible to false
  set Tableutama .Visible to true
  set Hitam .Enabled to true
  set luwak .Enabled to true
  set capucino .Enabled to true
  set deng1 .Enabled to true
  set gede1 .Enabled to true
  set deng2 .Enabled to true
  set gede2 .Enabled to true
  set deng3 .Enabled to true
  set gede3 .Enabled to true
  set memuatsaldo .Text to "0"
  set IDPelanggan .Text to "0"

```

```

when [deng1 .Click]
do
  set [memuatsaldo .Text] to [memuatsaldo .Text - 5000]
  call [TinyWebDB1 .StoreValue]
    tag [IDPelanggan .Text]
    valueToStore [memuatsaldo .Text]
  call [BluetoothClient1 .SendText]
    text ["s1"]
  set [tablekopi1 .Visible] to [false]
  set [Tablesaldo .Visible] to [false]
  set [tablekeluarbalik .Visible] to [false]
  set [Tableutama .Visible] to [true]
  set [Hitam .Enabled] to [true]
  set [luwak .Enabled] to [true]
  set [capucino .Enabled] to [true]
  set [deng1 .Enabled] to [true]
  set [gede1 .Enabled] to [true]
  set [deng2 .Enabled] to [true]
  set [deng2 .Enabled] to [true]
  set [gede2 .Enabled] to [true]
  set [deng3 .Enabled] to [true]
  set [gede3 .Enabled] to [true]
  set [memuatsaldo .Text] to [""]
  set [IDPelanggan .Text] to [""]

when [gede1 .Click]
do
  set [memuatsaldo .Text] to [memuatsaldo .Text + 6000]
  call [TinyWebDB1 .StoreValue]
    tag [IDPelanggan .Text]
    valueToStore [memuatsaldo .Text]
  call [BluetoothClient1 .SendText]
    text ["b1"]
  set [tablekopi1 .Visible] to [false]
  set [Tablesaldo .Visible] to [false]
  set [tablekeluarbalik .Visible] to [false]
  set [Tableutama .Visible] to [true]
  set [Hitam .Enabled] to [true]
  set [luwak .Enabled] to [true]
  set [capucino .Enabled] to [true]
  set [deng1 .Enabled] to [true]
  set [gede1 .Enabled] to [true]
  set [deng2 .Enabled] to [true]
  set [gede2 .Enabled] to [true]
  set [deng3 .Enabled] to [true]
  set [gede3 .Enabled] to [true]
  set [memuatsaldo .Text] to [""]
  set [IDPelanggan .Text] to [""]

```

**when cil2 . Click**

```

do set memuatsaldo . Text to memuatsaldo . Text - ( 5000 )
call TinyWebDB1 . StoreValue
    tag IDPelanggan . Text
    valueToStore memuatsaldo . Text
call BluetoothClient1 . SendText
    text " k2 "
set tablekopi2 . Visible to false
set Tablesaldo . Visible to false
set tablekeluarbalik . Visible to false
set Tableutama . Visible to true
set Hitam . Enabled to true
set luwak . Enabled to true
set capucino . Enabled to true
set deng1 . Enabled to true
set gede1 . Enabled to true
set deng2 . Enabled to true
set gede2 . Enabled to true
set deng3 . Enabled to true
set gede3 . Enabled to true
set memuatsaldo . Text to " 0 "
set IDPelanggan . Text to " 0 "

```

**when deng2 . Click**

```

do set memuatsaldo . Text to memuatsaldo . Text - ( 6000 )
call TinyWebDB1 . StoreValue
    tag IDPelanggan . Text
    valueToStore memuatsaldo . Text
call BluetoothClient1 . SendText
    text " s2 "
set tablekopi2 . Visible to false
set Tablesaldo . Visible to false
set tablekeluarbalik . Visible to false
set Tableutama . Visible to true
set Hitam . Enabled to true
set luwak . Enabled to true
set capucino . Enabled to true
set deng1 . Enabled to true
set gede1 . Enabled to true
set deng2 . Enabled to true
set gede2 . Enabled to true
set deng3 . Enabled to true
set gede3 . Enabled to true
set memuatsaldo . Text to " 0 "
set IDPelanggan . Text to " 0 "

```

**when gede2 .Click**

```

do set memuatsaldo . Text to memuatsaldo . Text - ( 7000 )
call TinyWebDB1 . StoreValue
    tag IDPelanggan . Text
    valueToStore memuatsaldo . Text
call BluetoothClient1 . SendText
    text " b2 "
set tablekopi2 . Visible to false
set Tablesaldo . Visible to false
set tablekeluarbalik . Visible to false
set Tableutama . Visible to true
set Hitam . Enabled to true
set luwak . Enabled to true
set capucino . Enabled to true
set deng1 . Enabled to true
set gede1 . Enabled to true
set deng2 . Enabled to true
set gede2 . Enabled to true
set deng3 . Enabled to true
set gede3 . Enabled to true
set memuatsaldo . Text to " "
set IDPelanggan . Text to " "

```

**when cil3 .Click**

```

do set memuatsaldo . Text to memuatsaldo . Text - ( 7000 )
call TinyWebDB1 . StoreValue
    tag IDPelanggan . Text
    valueToStore memuatsaldo . Text
call BluetoothClient1 . SendText
    text " k3 "
set tablekopi3 . Visible to false
set Tablesaldo . Visible to false
set tablekeluarbalik . Visible to false
set Tableutama . Visible to true
set Hitam . Enabled to true
set luwak . Enabled to true
set capucino . Enabled to true
set deng1 . Enabled to true
set gede1 . Enabled to true
set deng2 . Enabled to true
set gede2 . Enabled to true
set deng3 . Enabled to true
set gede3 . Enabled to true
set memuatsaldo . Text to " "
set IDPelanggan . Text to " "

```

```

when deng3 .Click
do
  set memuatsaldo .Text to memuatsaldo .Text - [ 8000 ]
  call TinyWebDB1 .StoreValue
    tag IDPelanggan .Text
    valueToStore memuatsaldo .Text
  call BluetoothClient1 .SendText
    text " s3 "
  set tablekopi3 .Visible to false
  set Tablesaldo .Visible to false
  set tablekeluarbalik .Visible to false
  set Tableutama .Visible to true
  set Hitam .Enabled to true
  set luwak .Enabled to true
  set capucino .Enabled to true
  set deng1 .Enabled to true
  set gede1 .Enabled to true
  set deng2 .Enabled to true
  set gede2 .Enabled to true
  set deng3 .Enabled to true
  set gede3 .Enabled to true
  set memuatsaldo .Text to " "
  set IDPelanggan .Text to " "
when gede3 .Click
do
  set memuatsaldo .Text to memuatsaldo .Text + [ 10000 ]
  call TinyWebDB1 .StoreValue
    tag IDPelanggan .Text
    valueToStore memuatsaldo .Text
  call BluetoothClient1 .SendText
    text " b3 "
  set tablekopi3 .Visible to false
  set Tablesaldo .Visible to false
  set tablekeluarbalik .Visible to false
  set Tableutama .Visible to true
  set Hitam .Enabled to true
  set luwak .Enabled to true
  set capucino .Enabled to true
  set deng1 .Enabled to true
  set gede1 .Enabled to true
  set deng2 .Enabled to true
  set gede2 .Enabled to true
  set deng3 .Enabled to true
  set gede3 .Enabled to true
  set memuatsaldo .Text to " "
  set IDPelanggan .Text to " "

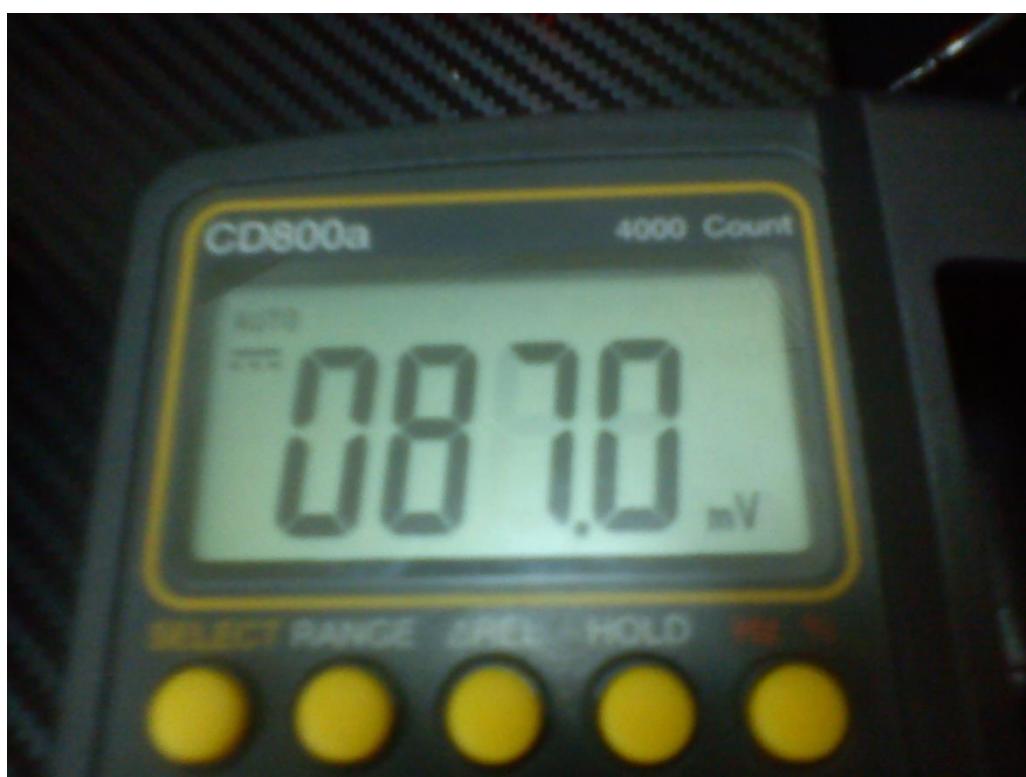
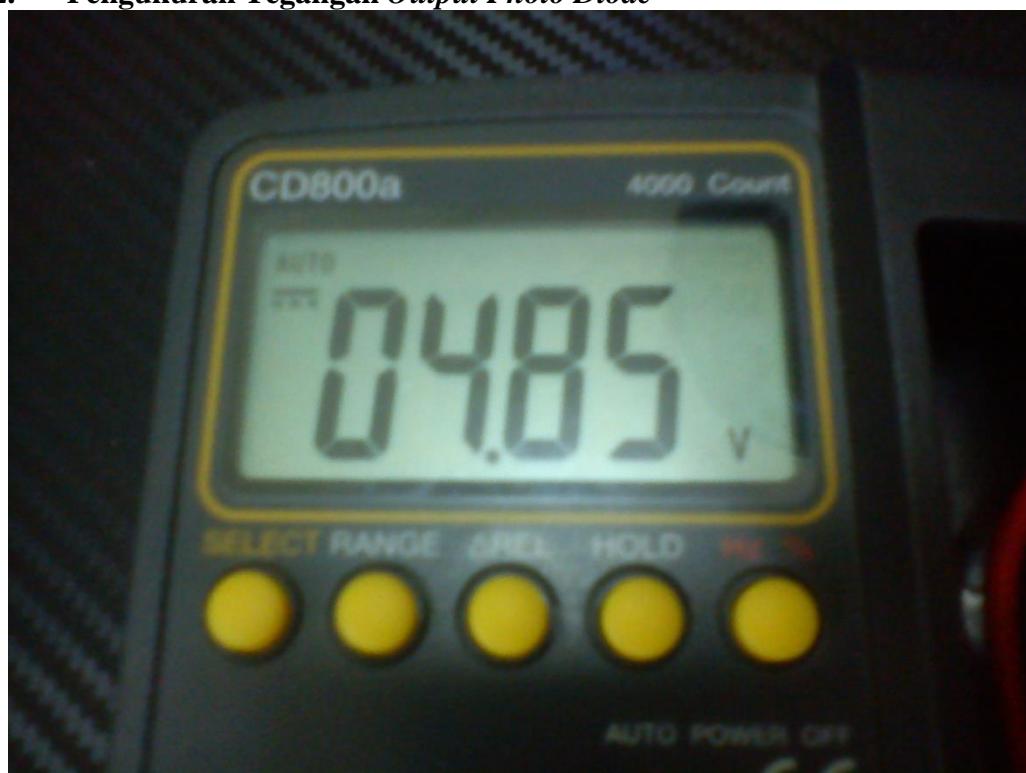
```

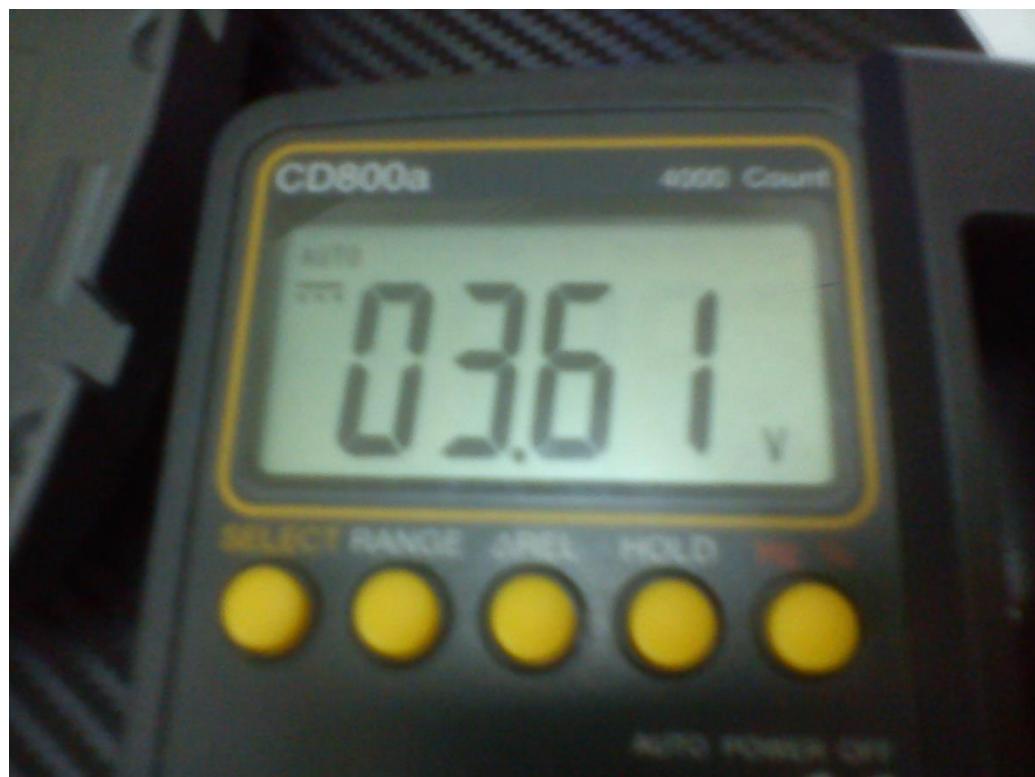
### Lampiran 3 Foto Pengukuran

#### 1. Pengukuran Tegangan *Output* Catu Daya



2. Pengukuran Tegangan Output Photo Diode



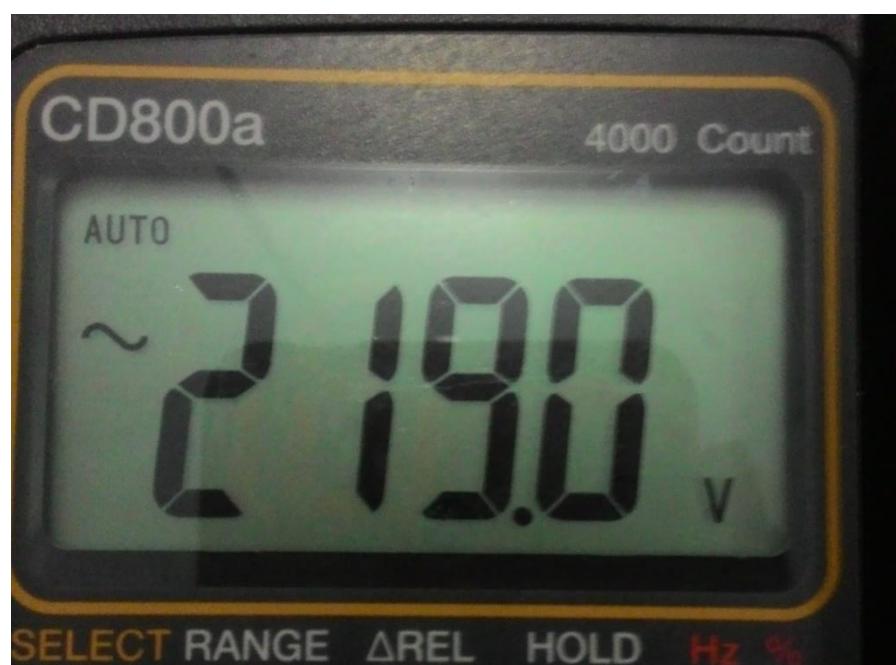




### 3. Pengukuran Tegangan *Output* Kran Elektrik



**4. Pengukuran Tegangan *Output* Relay Pemanas**





5. Pengukuran Tegangan *Output Pin Arduino*



## Riwayat Hidup



**Muhammad Ashif**, lahir di Jakarta, 19 Desember 1992. Penulis bertempat tinggal di Jl. Guji Baru, kecamatan Kebon Jeruk, kelurahan Duri Kepa, Jakarta Barat. Mahasiswa yang hobi browsing, bermain futsal dan membaca ini, pernah menempuh pendidikan dasar di SD Islam Al-Isra Jakarta. Setelah itu, penulis melanjutkan pendidikan menengah di SMPN 89 Jakarta dan SMAN 85 Jakarta. Setelah menyelesaikan pendidikan SMA, penulis melanjutkan pendidikan ke jenjang lebih tinggi di Universitas Negeri Jakarta Jurusan Teknik Elektro Program Studi Pendidikan Teknik Elektronika. Penulis dapat dihubungi melalui alamat e-mail di [ashif.192@gmail.com](mailto:ashif.192@gmail.com).